
p -Laplacian Based Graph Neural Networks

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This paper [1] considered the problem of semi-supervised node classification on heterophilic graphs and graphs with noisy edges. To this end, this paper derived a novel p -Laplacian message passing scheme from a discrete regularization framework and proposed a new p GNN architecture, which can be theoretically verified as an approximation of a polynomial graph filter defined on the spectral domain of the p -Laplacian. They theoretically demonstrate their method works as low-pass and high-pass filters and thereby applicable to both homophilic and heterophilic graphs.

1 Preliminaries and Background

Definition 1 (Graph Gradient). Given a graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ and a function $f : \mathcal{V} \rightarrow \mathbb{R}$, the graph gradient is an operator $\nabla : \mathcal{F}_{\mathcal{V}} \rightarrow \mathcal{F}_{\mathcal{E}}$ defined by

$$(\nabla f)([i, j]) = \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) - \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i), \quad \forall [i, j] \in \mathcal{E}. \quad (1)$$

For $[i, j] \notin \mathcal{E}$, $(\nabla f)([i, j]) = 0$. The graph gradient of a function f at vertex i is defined to be $(\nabla f)(i) = ((\nabla f)([i, 1]), \dots, (\nabla f)([i, N]))$ and its Frobenius norm is given by $\|(\nabla f)(i)\|_2 = \left(\sum_{j=1}^N (\nabla f)^2([i, j]) \right)^{\frac{1}{2}}$, which measures the variation of f around node i . We measure the variation of f over the whole graph \mathcal{G} by $\mathcal{S}_p(f)$ where it is defined to be

$$\mathcal{S}_p(f) = \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \|(\nabla f)([i, j])\|^p = \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \left\| \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) - \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) \right\|^p, \quad \text{for } p \geq 1.$$

Definition 2 (Graph Divergence). Given a graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ and functions $f : \mathcal{V} \rightarrow \mathbb{R}$, $g : \mathcal{E} \rightarrow \mathbb{R}$, the graph divergence is computed as

$$(\text{div}g)(i) = \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{i,i}}} (g([i, j]) - g([j, i])). \quad (2)$$

Definition 3 (Graph p -Laplacian Operator). Given a graph $\mathcal{G} = (\mathcal{V}, \mathcal{E})$ and a function $f : \mathcal{V} \rightarrow \mathbb{R}$, the graph p -Laplacian is an operator $\Delta_p : \mathcal{F}_{\mathcal{V}} \rightarrow \mathcal{F}_{\mathcal{V}}$ defined by

$$\Delta_p f = -\frac{1}{2} \text{div} \left(\|\nabla f\|^{p-2} \nabla f \right), \quad \text{for } p \geq 1, \quad (3)$$

where $\|\cdot\|^{p-2}$ is element-wise.

Substituting Eq. (1) and Eq. (2) into Eq. (3), we obtain

$$\begin{aligned}
& (\Delta_p f)(i) \\
&= -\frac{1}{2} \operatorname{div} \left(\|\nabla f\|^{p-2} \nabla f \right) (i) \tag{4} \\
&= -\frac{1}{2} \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{i,i}}} \left((\|\nabla f\|^{p-2} \nabla f) ([i, j]) - (\|\nabla f\|^{p-2} \nabla f) ([j, i]) \right) \\
&= \frac{1}{2} \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{i,i}}} \left(\|\nabla f ([j, i])\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) - \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) \right) \right) - \|\nabla f [i, j]\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) - \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) \right) \\
&= \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{i,i}}} \left(\|\nabla f [j, i]\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) - \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) \right) \right). \tag{5}
\end{aligned}$$

When $p = 2$, $\Delta_2 = \mathbf{I} - \mathbf{D}^{-1/2} \mathbf{W} \mathbf{D}^{-1/2}$ is referred as the ordinary Laplacian operator. When $p = 1$, $\Delta_1 = -\frac{1}{2} \operatorname{div} \left(\|\nabla f\|^{-1} \nabla f \right)$ is referred as the curvature operator. Note that Laplacian Δ_2 is a linear operator, while in general for $p \neq 2$, p -Laplacian is nonlinear since $\Delta_p (af) \neq a \Delta_p (f)$ for $a \in \mathbb{R}$.

The graph p -Laplacian is semi-definite:

$$\begin{aligned}
\langle f, \Delta_p f \rangle &= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{i,i}}} \|\nabla f ([j, i])\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) - \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) \right) f(i) \\
&\quad - \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \sqrt{\frac{W_{i,j}}{D_{j,j}}} \|\nabla f [j, i]\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) - \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) \right) f(j) \\
&= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \|\nabla f ([j, i])\|^{p-2} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) f(i) + \sqrt{\frac{W_{i,j}}{D_{j,j}}} \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) f(j) - 2 \sqrt{\frac{W_{i,j}}{D_{i,i}}} \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(i) f(j) \right) \\
&= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \|\nabla f ([j, i])\|^{p-2} \|\nabla f ([j, i])\|^2 \\
&= \frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N \|\nabla f ([i, j])\|^p \\
&= \mathcal{S}_p (f) \geq 0.
\end{aligned}$$

We also have

$$\begin{aligned}
\frac{\partial \mathcal{S}_p (f)}{\partial f} \Big|_i &= \frac{\partial \left(\sum_{j=1}^N \|\nabla f ([i, j])\|^p - \|\nabla f ([i, i])\|^p \right)}{\partial f (i)} \\
&= \frac{\partial \left(\sum_{j=1}^N \left\| \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) - \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) \right\|^p \right)}{\partial f (i)} \\
&= \sum_{j=1}^N \frac{p}{2} \left\| \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) - \sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) \right\|^{p-2} 2 \sqrt{\frac{W_{i,j}}{D_{i,i}}} \left(\sqrt{\frac{W_{i,j}}{D_{i,i}}} f(i) - \sqrt{\frac{W_{i,j}}{D_{j,j}}} f(j) \right) \\
&= p (\Delta_p f) (i).
\end{aligned}$$

2 p -Laplacian Based Graph Neural Networks

The p -Laplacian regularization problem is defined to be

$$\mathbf{F}^* = \arg \min_{\mathbf{F}} \mathcal{L}_p(\mathbf{F}) := \arg \min_{\mathbf{F}} \mathcal{S}_p(\mathbf{F}) + \mu \sum_{i=1}^N \|\mathbf{F}_{i,:} - \mathbf{X}_{i,:}\|^2, \quad (6)$$

where $\mu \in (0, \infty)$. Different choices of p result in different smoothness constraint on the signals.

With $p = 2$, the p -Laplacian regularization problem has closed-form solution which corresponds to PPNP.

For $p > 1$, the gradient of $\mathcal{L}_p(\mathbf{F})$ over $\mathbf{F}_{i,:}$, for all $i \in [N]$ is

$$\frac{\partial \mathcal{L}_p(\mathbf{F})}{\partial \mathbf{F}_{i,:}} = p \sum_{j=1}^N \frac{W_{i,j}}{\sqrt{D_{i,i}}} \left(\left\| \sqrt{\frac{W_{i,j}}{D_{i,i}}} \mathbf{F}_{i,:} - \sqrt{\frac{W_{i,j}}{D_{j,j}}} \mathbf{F}_{j,:} \right\|^{p-2} \left(\frac{1}{\sqrt{D_{i,i}}} \mathbf{F}_{i,:} - \frac{1}{\sqrt{D_{j,j}}} \mathbf{X}_{i,:} \right) \right) + \frac{2\mu}{p} (\mathbf{F}_{i,:} - \mathbf{X}_{i,:}).$$

Using gradient descent with stepsize $\frac{\alpha_{i,i}^{(k)}}{p}$ where

$$\alpha_{i,i}^{(k)} = 1 / \left(\sum_{j=1}^N \frac{M_{i,j}^{(k)}}{D_{i,i}} + \frac{2\mu}{p} \right), \quad \forall i \in [N],$$

$$M_{i,j}^{(k)} = W_{i,j} \left\| \sqrt{\frac{W_{i,j}}{D_{i,i}}} \mathbf{F}_{i,:}^{(k)} - \sqrt{\frac{W_{i,j}}{D_{j,j}}} \mathbf{F}_{j,:}^{(k)} \right\|^{p-2}, \quad \forall i, j \in [N],$$

and denoting $\beta_{i,i}^{(k)} = \frac{2\mu}{p} \alpha_{i,i}^{(k)}$, $\forall i \in [N]$, then we have

$$\begin{aligned} & \mathbf{F}_{i,:}^{(k+1)} \\ &= \mathbf{F}_{i,:}^{(k)} - \frac{\alpha_{i,i}^{(k)}}{p} \left(p \sum_{j=1}^N \frac{W_{i,j}}{\sqrt{D_{i,i}}} \left(\left\| \sqrt{\frac{W_{i,j}}{D_{i,i}}} \mathbf{F}_{i,:}^{(k)} - \sqrt{\frac{W_{i,j}}{D_{j,j}}} \mathbf{F}_{j,:}^{(k)} \right\|^{p-2} \left(\frac{1}{\sqrt{D_{i,i}}} \mathbf{F}_{i,:}^{(k)} - \frac{1}{\sqrt{D_{j,j}}} \mathbf{F}_{j,:}^{(k)} \right) \right) + 2\mu (\mathbf{F}_{i,:} - \mathbf{X}_{i,:}) \right) \\ &= \mathbf{F}_{i,:}^{(k)} - \alpha_{i,i}^{(k)} \sum_{j=1}^N \frac{M_{i,j}^{(k)}}{\sqrt{D_{i,i}}} \left(\frac{1}{\sqrt{D_{i,i}}} \mathbf{F}_{i,:}^{(k)} - \frac{1}{\sqrt{D_{j,j}}} \mathbf{F}_{j,:}^{(k)} \right) - \beta_{i,i}^{(k)} (\mathbf{F}_{i,:} - \mathbf{X}_{i,:}) \\ &= \left(1 - \alpha_{i,i}^{(k)} \sum_{j=1}^N \frac{M_{i,j}^{(k)}}{D_{i,i}} - \beta_{i,i}^{(k)} \right) \mathbf{F}_{i,:}^{(k)} + \alpha_{i,i}^{(k)} \sum_{j=1}^N \frac{M_{i,j}^{(k)}}{\sqrt{D_{i,i} D_{j,j}}} \mathbf{F}_{j,:}^{(k)} + \beta_{i,i}^{(k)} \mathbf{X}_{i,:} \\ &= \left(1 - \alpha_{i,i}^{(k)} \left(\sum_{j=1}^N \frac{M_{i,j}^{(k)}}{D_{i,i}} + \frac{2\mu}{p} \right) \right) \mathbf{F}_{i,:}^{(k)} + \alpha_{i,i}^{(k)} \sum_{j=1}^N \frac{M_{i,j}^{(k)}}{\sqrt{D_{i,i} D_{j,j}}} \mathbf{F}_{j,:}^{(k)} + \beta_{i,i}^{(k)} \mathbf{X}_{i,:} \\ &= \alpha_{i,i}^{(k)} \sum_{j=1}^N \frac{M_{i,j}^{(k)}}{\sqrt{D_{i,i} D_{j,j}}} \mathbf{F}_{j,:}^{(k)} + \beta_{i,i}^{(k)} \mathbf{X}_{i,:}. \end{aligned}$$

Let $\mathbf{M}^{(k)} \in \mathbb{R}^{N \times N}$, $\boldsymbol{\alpha}^{(k)} = \text{diag}(\alpha_{1,1}^{(k)}, \dots, \alpha_{N,N}^{(k)})$, $\boldsymbol{\beta}^{(k)} = \text{diag}(\beta_{1,1}^{(k)}, \dots, \beta_{N,N}^{(k)})$, we can rewrite the above gradient step in matrix form as follows:

$$\mathbf{F}^{(k+1)} = \boldsymbol{\alpha}^{(k)} \mathbf{D}^{-1/2} \mathbf{M}^{(k)} \mathbf{D}^{-1/2} \mathbf{F}^{(k)} + \boldsymbol{\beta}^{(k)} \mathbf{X}.$$

It is easy to see that APPNP is a special case of this message passing scheme with $p = 2$. The convergence can be guaranteed with suitable stepsize.

Using this p -Laplacian message passing scheme, the p GNN is defined as follows:

$$\begin{aligned} \mathbf{F}^{(0)} &= \text{ReLU}(\mathbf{X} \boldsymbol{\Theta}^{(1)}) \\ \mathbf{F}^{(k+1)} &= \boldsymbol{\alpha}^{(k)} \mathbf{D}^{-1/2} \mathbf{M}^{(k)} \mathbf{D}^{-1/2} \mathbf{F}^{(k)} + \boldsymbol{\beta}^{(k)} \mathbf{F}^{(0)}, \quad k = 0, \dots, K-1, \\ \mathbf{Z} &= \text{softmax}(\mathbf{F}^{(K)} \boldsymbol{\Theta}^{(2)}). \end{aligned}$$

Some other theoretical analyses made in the paper such as the upperbound of the risk and the spectral analysis with p -Laplacian are also interesting.

References

- [1] Guoji Fu, Peilin Zhao, and Yatao Bian. p -laplacian based graph neural networks. *arXiv preprint arXiv:2111.07337*, 2021. (document)